

Sysroots and Devroots

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Sysroots and devroots are two development rootfs meant to provide an environment to build software for Apertis, targeting foreign architecture that don't
match the CPU architecture of the build host (for instance, building ARM64
binaries from a Intel-based host).

¹² They are meant to address different use cases with different trade-offs.

¹³ Sysroot

Sysroots are file system trees specifically meant for cross-compilation and remote
 debugging targeting a specific release image.

They are meant to be read-only and target a specific release image, shipping
all the development headers and debug symbols for the libraries in the release
image.

Sysroots can be used to cross-compile for Apertis from a third-party environment using an appropriate cross-toolchain¹. They are most suited for early
development phases where developers focus on quick iterations and rely on fast
incremental builds of their components.

²³ Cross-compilation using sysroot requires support from the project build system,
²⁴ which then needs to be set up to appropriately point to the sysroot and to the
²⁵ cross compiler. Not all build systems support cross compilation and some may
²⁶ require patching to make it work properly.

The Apertis SDK ships the ade tool to simplify sysroots management and the configuration of projects based on the GNU Autotools² to use them, focusing in particular on application development. See the Apertis Development Environment³ guide for information on how to use ade.

Sysroots can be used without ade by manually downloading the sysroot tarball from the release artifact repository and then unpack it locally with tar, see the

¹https://jwd.pages.apertis.org/apertis-website/guides/cross-build-toolchain/

 $^{^{2}} https://www.gnu.org/software/automake/manual/html_node/Autotools-Introduction. html$

³https://jwd.pages.apertis.org/apertis-website/guides/ade/

instructions in the cross-toolchain documentation⁴ for a full walk-through on
 using them on non-Apertis hosts.

Since unpacked sysroots are self-contained folders, multiple sysroots can coexist on a single system to target multiple architectures and releases: for instance, a single system could host the armhf and arm64 sysroots for v2019pre and the arm64 one for v2020dev0 at the same time. Using the portable cross-build toolchain⁵ matching the target release is recommended.

40 Sysroots are available from the Apertis release artifact repository as sys 41 root*.tar.gz tarballs under the \$release/\$architecture/sysroot/ folder,
 42 for instance sysroot-apertis-v2019pre-arm64-v2019pre.0.tar.gz⁶ under
 43 v2019pre.0/arm64⁷.

44 Devroot

⁴⁵ Devroots are file system trees meant to offer a foreign architecture build envi ⁴⁶ ronment via containers and binary emulation via the QEMU user mode.

⁴⁷ Using emulation means that, for instance, all the binaries on the ARM64 devroot
⁴⁸ are ARM64 binaries and QEMU translates them at runtime to execute them on
⁴⁹ a Intel-based host.

This means that builds under a devroot appear to the build system as native builds and no special support or configuration is needed, unlike for actual cross builds using systems.

Devroots ship a minimal set of packages and offer the ability to install all the
 packages in the Apertis archive using the apt tool just like on the Apertis SDK
 itself.

⁵⁶ Due to the nature of foreign architecture emulation they impose a considerable
 ⁵⁷ overhead on build times compared to sysroot, but they avoid all the intricacies
 ⁵⁸ that cross-building involves and offer the ability to reliably build deb packages
 ⁵⁹ targeting foreign architectures.

⁶⁰ The Apertis SDK ships the devroot-enter tool to set up the container environ-⁶¹ ment needed to work in a unpacked devroot, see the "Programming guidelines"

 $_{62}$ section⁸ for information on how to use devroot-enter.

Since devroots are self-contained folders like systemets, multiple devroots may
 be installed at the same time on a single host to target multiple releases and
 architectures.

 $\label{eq:product} ^{5} https://jwd.pages.apertis.org/apertis-website/guides/cross-build-toolchain/$

 $^{6} \rm https://images.apertis.org/release/v2019pre/v2019pre.0/arm64/sysroot/sysroot-apertis-v2019pre-arm64-v2019pre.0.tar.gz$

⁷https://images.apertis.org/release/v2019pre/v2019pre.0/arm64/sysroot/

⁴https://jwd.pages.apertis.org/apertis-website/guides/cross-build-toolchain/

 $^{^{8} \}rm https://jwd.pages.apertis.org/apertis-website/guides/tooling/\#development-containers-using-devroot-enter$

66 Devroots are available from the Apertis release artifact repository as 67 the ospack*.tar.gz tarballs under the \$release/\$architecture/devroot/ 68 folder, for instance ospack_v2019pre-arm64-devroot_v2019pre.0.tar.gz⁹ un-69 der v2019pre.0/arm64¹⁰.

As of v2019pre, the Apertis SDK images come with the armhf devroot preinstalled.

72 A comparison

73 Sysroot

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Benefits

- Fast
 - No special requirements on the system
 - Supports remote debugging by providing symbols matching a specific target images
- 79 Drawbacks
 - Only works with build systems explicitly supporting cross-building
- Cannot be customized

82 Devroot

• Benefits

- Builds appears as native builds to build systems, avoiding cross compilation issues
 - Can be fully customized, adding, removing and updating packages
- Drawbacks
 - Requires a container to be set up on the host (systemd-nspawn is recommended)
 - Binary emulation imposes a significant performance overhead
- Supporting remote debugging requires additional care to ensure that
 - symbols match the software running on the target image

⁹³ When to use them

- For application and agent development building app-bundles: ⁹⁵ use the sysroot
 - This is the main use-case for using the sysroot and the ade tool is meant to simplify this workflow.
- For platform development building deb packages: use the devroot

⁹https://images.apertis.org/release/v2019pre/v2019pre.0/arm64/devroot/ospack_ v2019pre-arm64-devroot_v2019pre.0.tar.gz

 $^{^{10} \}rm https://images.apertis.org/release/v2019 pre/v2019 pre.0/arm64/devroot/$

100	- Support for cross-building deb packages is spotty, using the devroot
101	with devroot-enter provides the most reliable solution in this case
102	and enables developers to install extra dependencies not shipped on
103	Apertis images by default.
104	• To cross-build for Apertis from a third-party SDK: use the sys-
105	root
106	- If the build system already supports cross-building, using the system
107	does not pose additional requirements on the third-party SDK, while
108	the devroot requires emulation and a container setup.
109	• To build projects not supporting cross-compilation: use the de-
110	vroot
111	– The devroot is meant to emulate native compilation, side-stepping
112	any cross-compilation issue.
113	– On a third-party SDK it is still possible to use the devroot using the
114	devroot-enter script ¹¹ as long as the following tools are available and
115	set up:
116	st qemu-arm-static/qemu-aarch64-static (from the qemu-user-static
117	package) for foreign binary emulation
118	$* a binfmt_misc setup for transparent usage of qemu-user-static$
119	(provided by the binfmt-support package on Debian-based sys-
120	tems)
121	* systemd-nspawn (from the systemd-container package) for setting
122	up the containerized environment

 $[\]fbox{11} \\ https://gitlab.apertis.org/apertis/apertis-dev-tools/blob/apertis/v2019pre/tools/devroot-enter}$